NAG Fortran Library Routine Document F08KOF (ZGELSD)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

F08KQF (ZGELSD) computes the minimum norm solution to a real linear least-squares problem

$$\min_{x} \|b - Ax\|_2.$$

2 Specification

```
SUBROUTINE F08KQF (M, N, NRHS, A, LDA, B, LDB, S, RCOND, RANK, WORK, LWORK, RWORK, IWORK, INFO)

INTEGER

M, N, NRHS, LDA, LDB, RANK, LWORK, IWORK(*), INFO

double precision

complex*16

A(LDA,*), B(LDB,*), WORK(*)
```

The routine may be called by its LAPACK name zgelsd.

3 Description

F08KQF (ZGELSD) uses the singular value decomposition (SVD) of A, where A is an m by n matrix which may be rank-deficient.

Several right-hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the b0 t1 right-hand side matrix t2 and the t2 solution matrix t3.

The problem is solved in three steps:

- 1. reduce the coefficient matrix A to bidiagonal form with Householder transformations, reducing the original problem into a 'bidiagonal least-squares problem' (BLS);
- 2. solve the BLS using a divide-and-conquer approach;
- 3. apply back all the Householder transformations to solve the original least-squares problem.

The effective rank of A is determined by treating as zero those singular values which are less than RCOND times the largest singular value.

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia URL: http://www.netlib.org/lapack/lug

Golub G H and Van Loan C F (1996) Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

M - INTEGER Input

On entry: m, the number of rows of the matrix A.

Constraint: $M \ge 0$.

2: N – INTEGER Input

On entry: n, the number of columns of the matrix A.

Constraint: $N \ge 0$.

3: NRHS – INTEGER Input

On entry: r, the number of right-hand sides, i.e., the number of columns of the matrices B and X. Constraint: NRHS ≥ 0 .

4: A(LDA,*) - complex*16 array

Input/Output

Note: the second dimension of the array A must be at least max(1, N).

On entry: the m by n matrix A.

On exit: the contents of A are destroyed.

5: LDA – INTEGER Input

On entry: the first dimension of the array A as declared in the (sub)program from which F08KQF (ZGELSD) is called.

Constraint: LDA $> \max(1, M)$.

6: B(LDB,*) - complex*16 array

Input/Output

Note: the second dimension of the array B must be at least max(1, NRHS).

On entry: the m by r right-hand side matrix B.

On exit: is overwritten by the n by r solution matrix X. If $m \ge n$ and RANK = n, the residual sum of squares for the solution in the ith column is given by the sum of squares of the modulus of elements $n+1,\ldots,m$ in that column.

7: LDB – INTEGER Input

On entry: the first dimension of the array B as declared in the (sub)program from which F08KQF (ZGELSD) is called.

Constraint: LDB $\geq \max(1, M, N)$.

8: S(*) – *double precision* array

Output

Note: the dimension of the array S must be at least max(1, min(M, N)).

On exit: the singular values of A in decreasing order.

9: RCOND – double precision

Input

On entry: used to determine the effective rank of A. Singular values $S(i) \le RCOND \times S(1)$ are treated as zero. If RCOND < 0, machine precision is used instead.

10: RANK – INTEGER

Output

On exit: the effective rank of A, i.e., the number of singular values which are greater than RCOND \times S(1).

11: WORK(*) - complex*16 array

Workspace

Note: the dimension of the array WORK must be at least max(1, LWORK).

On exit: if INFO = 0, the real part of WORK(1) contains the minimum value of LWORK required for optimal performance.

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12: LWORK – INTEGER

Input

On entry: the dimension of the array WORK as declared in the (sub)program from which F08KQF (ZGELSD) is called.

The exact minimum amount of workspace needed depends on M, N and NRHS. As long as LWORK is at least

$$\max(1, M + N + r, 2r + r \times NRHS)$$
,

where $r = \min(M, N)$, the code will execute correctly.

If LWORK =-1, a workspace query is assumed; the routine only calculates the optimal size of the WORK array and the minimum size of the IWORK array, and returns these values as the first entries of the WORK and IWORK arrays, and no error message related to LWORK is issued.

Suggested value: for optimal performance, LWORK should generally be larger than the required minimum. Consider increasing LWORK by at least $nb \times \min(M, N)$, where nb is the optimal **block** size.

Constraint: LWORK must be at least $max(1, M + N + r, 2r + r \times NRHS)$ or LWORK = -1.

13: RWORK(*) – *double precision* array

Workspace

Note: the dimension of the array RWORK must be at least max(1, lrwork), where lrwork is at least

$$10 \times N + 2 \times N \times smlsiz + 8 \times N \times nlvl + 3 \times smlsiz \times NRHS + (smlsiz + 1)^2$$
, if $M \ge N$ or

$$10 \times M + 2 \times M \times smlsiz + 8 \times M \times nlvl + 3 \times smlsiz \times NRHS + (smlsiz + 1)^2$$
, if $M < N$

where smlsiz is equal to the maximum size of the subproblems at the bottom of the computation tree (usually about 25), and $nlvl = \max(0, \inf(\log_2(\min(M, N)/(smlsiz + 1))) + 1)$, the code will execute correctly.

On exit: if INFO = 0, RWORK(1) contains the required minimal size of lrwork.

14: IWORK(*) - INTEGER array

Workspace

Note: the dimension of the array IWORK must be at least $\max(1, liwork)$, where liwork is at least $\max(1, 3 \times \min(M, N) \times nlvl + 11 \times \min(M, N))$.

On exit: if INFO = 0, IWORK(1) returns the minimum liwork.

15: INFO – INTEGER Output

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the routine:

INFO < 0

If INFO = -i, the *i*th parameter had an illegal value. An explanatory message is output, and execution of the program is terminated.

INFO > 0

The algorithm for computing the SVD failed to converge; if INFO = i, i off-diagonal elements of an intermediate bidiagonal form did not converge to zero.

7 Accuracy

See Section 4.5 of Anderson et al. (1999) for details.

8 Further Comments

The real analogue of this routine is F08KCF (DGELSD).

9 Example

This example solves the linear least-squares problem

$$\min_{x} \|b - Ax\|_2$$

for the solution, x, of minimum norm, where

$$A = \begin{pmatrix} 0.47 - 0.34i & -0.32 - 0.23i & 0.35 - 0.60i & 0.89 + 0.71i & -0.19 + 0.06i \\ -0.40 + 0.54i & -0.05 + 0.20i & -0.52 - 0.34i & -0.45 - 0.45i & 0.11 - 0.85i \\ 0.60 + 0.01i & -0.26 - 0.44i & 0.87 - 0.11i & -0.02 - 0.57i & 1.44 + 0.80i \\ 0.80 - 1.02i & -0.43 + 0.17i & -0.34 - 0.09i & 1.14 - 0.78i & 0.07 + 1.14i \end{pmatrix}$$

and

$$b = \begin{pmatrix} 2.15 - 0.20i \\ -2.24 + 1.82i \\ 4.45 - 4.28i \\ 5.70 - 6.25i \end{pmatrix}.$$

A tolerance of 0.01 is used to determine the effective rank of A.

Note that the block size (NB) of 64 assumed in this example is not realistic for such a small problem, but should be suitable for large problems.

9.1 Program Text

```
FO8KQF Example Program Text
Mark 21 Release. NAG Copyright 2004.
 .. Parameters ..
                       LRWORK=1
INTEGER
PARAMETER
(NIN=5,NOUT=6)
INTEGER
MMAX, NB, NLVL, NMAX, SMLSIZ
PARAMETER
(MMAX=8,NB=64,NLVL=10,NMAX=16,SMLSIZ=25)
INTEGER
LDA, LIWORK, LRWORK, LWORK
PARAMETER
(LDA=MMAX,LIWORK=3*MMAX*NLVL+11*MMAX,
LRWORK=10*MMAX+2*MMAX*SMLSIZ+8*MMAX*NLVL+3*
SMI.SIZ+(SMLSIZ+1)**2,LWORK=2*MMAX+NB*(MMAX+1)
                      SMLSIZ+(SMLSIZ+1)**2,LWORK=2*MMAX+NB*(MMAX+NMAX))
DOUBLE PRECISION RCOND
 INTEGER
                       I, INFO, J, M, N, RANK
.. Local Arrays .. COMPLEX *16 A(LDA,NMAX), B(NMAX), WORK(LWORK)
DOUBLE PRECISION RWORK(LRWORK), S(MMAX)
INTEGER
              IWORK(LIWORK)
 .. External Subroutines
EXTERNAL
                 ZGELSD
 .. Executable Statements ..
WRITE (NOUT,*) 'F08KQF Example Program Results'
WRITE (NOUT, *)
Skip heading in data file
READ (NIN,*)
READ (NIN,*) M, N
IF (M.LE.MMAX .AND. N.LE.NMAX .AND. M.LE.N) THEN
     Read A and B from data file
     READ (NIN, *) ((A(I,J), J=1, N), I=1, M)
     READ (NIN, \star) (B(I), I=1, M)
     Choose RCOND to reflect the relative accuracy of the input
     data
```

```
RCOND = 0.01D0
         Solve the least squares problem min( norm2(b - Ax) ) for the
        x of minimum norm.
        CALL ZGELSD(M,N,1,A,LDA,B,N,S,RCOND,RANK,WORK,LWORK,RWORK,
                     IWORK, INFO)
        IF (INFO.EQ.O) THEN
           Print solution
            WRITE (NOUT,*) 'Least squares solution'
            WRITE (NOUT, 99999) (B(I), I=1, N)
            Print the effective rank of A
            WRITE (NOUT, *)
            WRITE (NOUT,*) 'Tolerance used to estimate the rank of A'
            WRITE (NOUT, 99998) RCOND
            WRITE (NOUT, *) 'Estimated rank of A'
            WRITE (NOUT, 99997) RANK
            Print singular values of A
            WRITE (NOUT,*)
            WRITE (NOUT,*) 'Singular values of A'
            WRITE (NOUT, 99996) (S(I), I=1, M)
         ELSE IF (INFO.GT.O) THEN
            WRITE (NOUT,*) 'The SVD algorithm failed to converge'
         END IF
         WRITE (NOUT,*) 'MMAX and/or NMAX too small, and/or M.GT.N'
      END IF
     STOP
99999 FORMAT (4(' (',F7.4,',',F7.4,')',:))
99998 FORMAT (3X,1P,E11.2)
99997 FORMAT (1X,16)
99996 FORMAT (1X,7F11.4)
     END
```

9.2 Program Data

(-2.24, 1.82) (4.45,-4.28) (5.70,-6.25)

F08KQF Example Program Data

```
4 5 :Values of M and N

( 0.47,-0.34) (-0.32,-0.23) ( 0.35,-0.60) ( 0.89, 0.71) (-0.19, 0.06) (-0.40, 0.54) (-0.05, 0.20) (-0.52,-0.34) (-0.45,-0.45) ( 0.11,-0.85) ( 0.60, 0.01) (-0.26,-0.44) ( 0.87,-0.11) (-0.02,-0.57) ( 1.44, 0.80) ( 0.80,-1.02) (-0.43, 0.17) (-0.34,-0.09) ( 1.14,-0.78) ( 0.07, 1.14) :End of A

( 2.15,-0.20)
```

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:End of vector b

9.3 Program Results